

# Analyzing Delays in Trajectories

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**Where innovation starts**

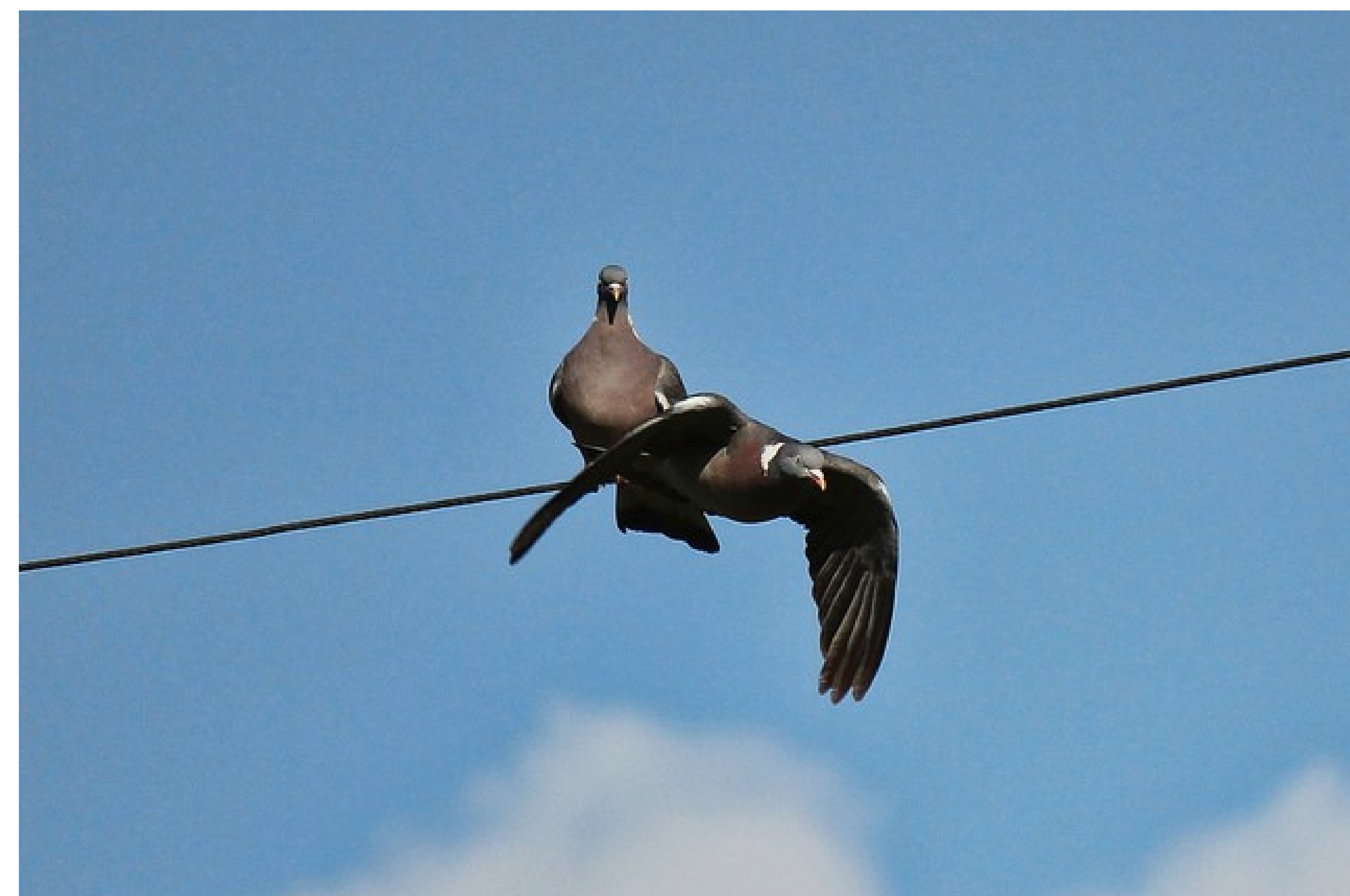
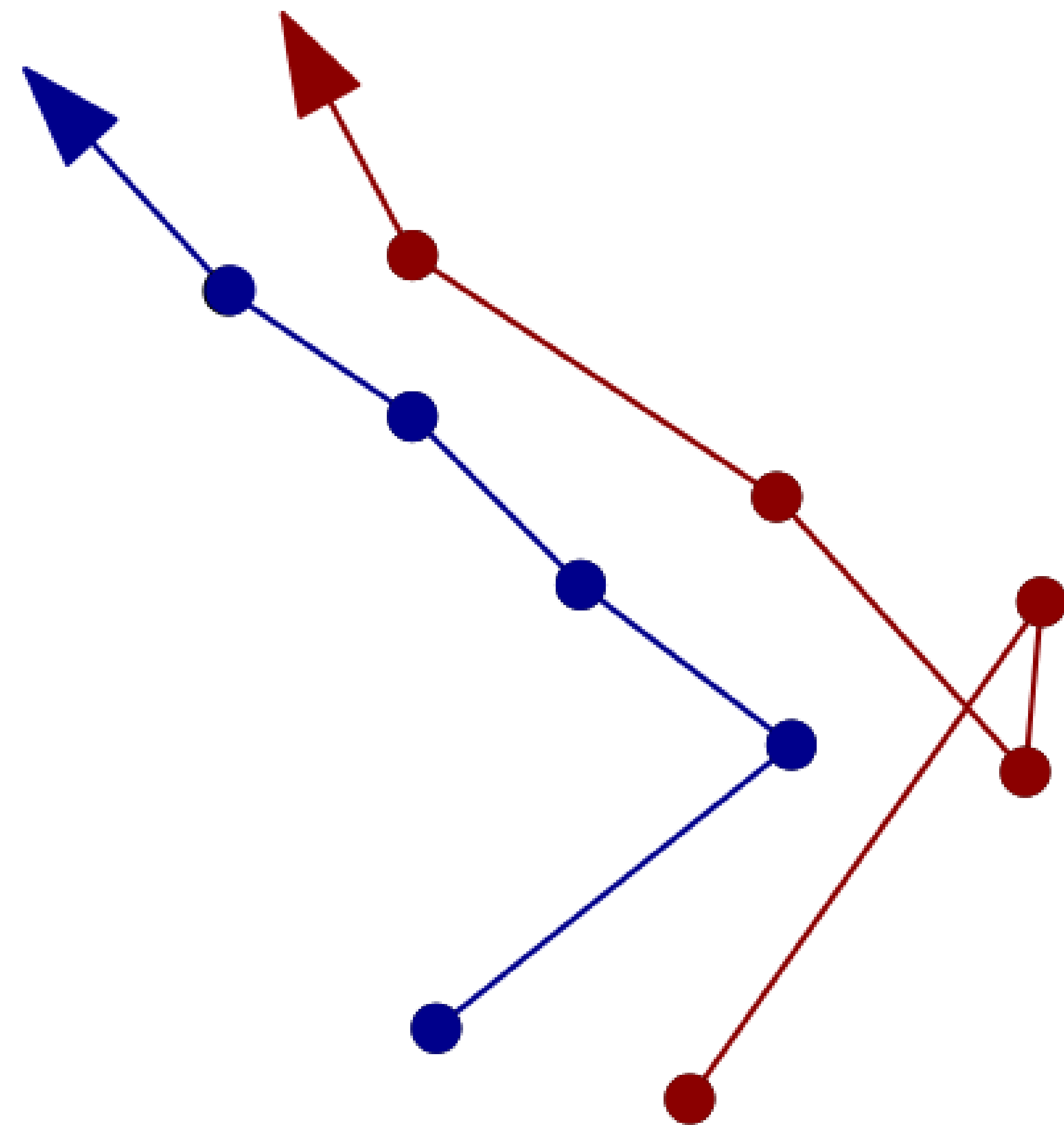


## What is interaction?

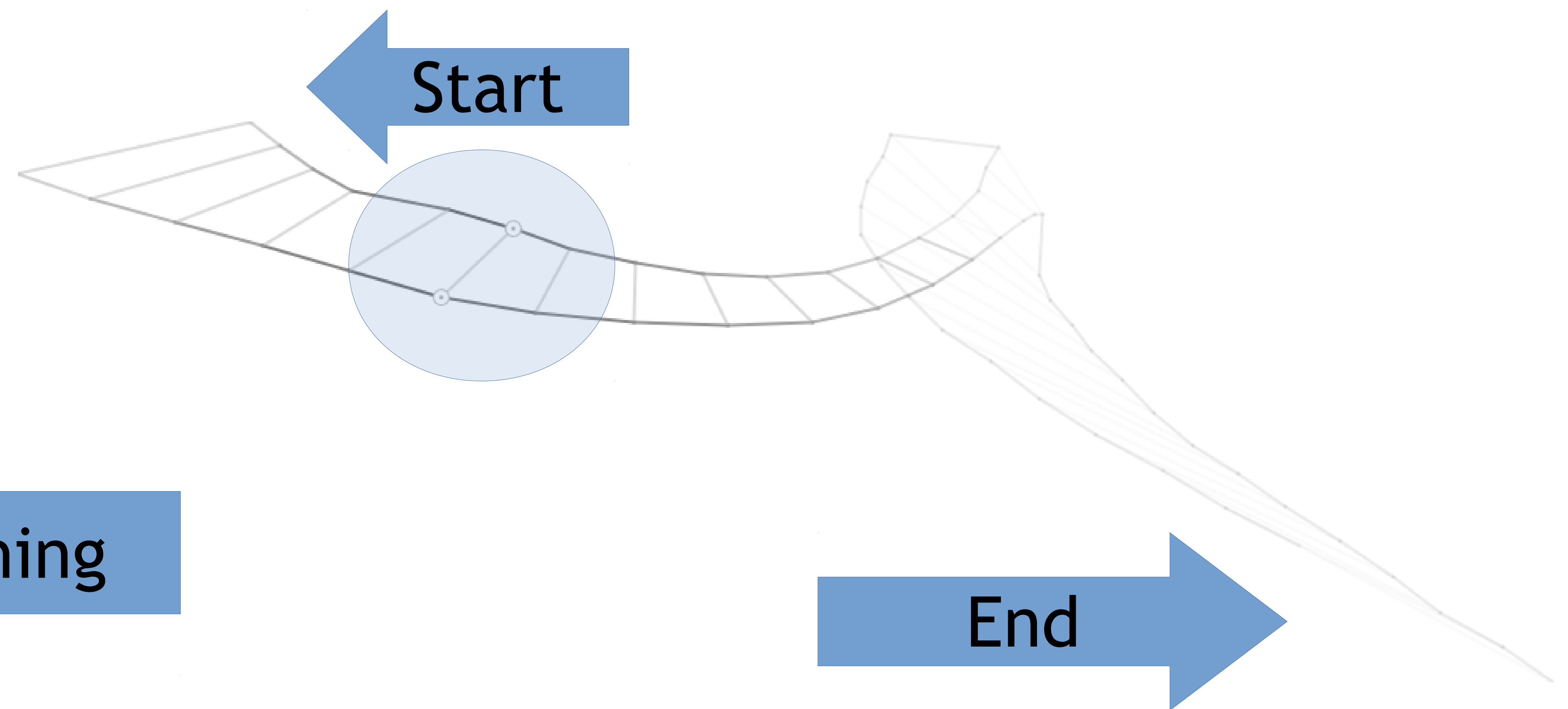
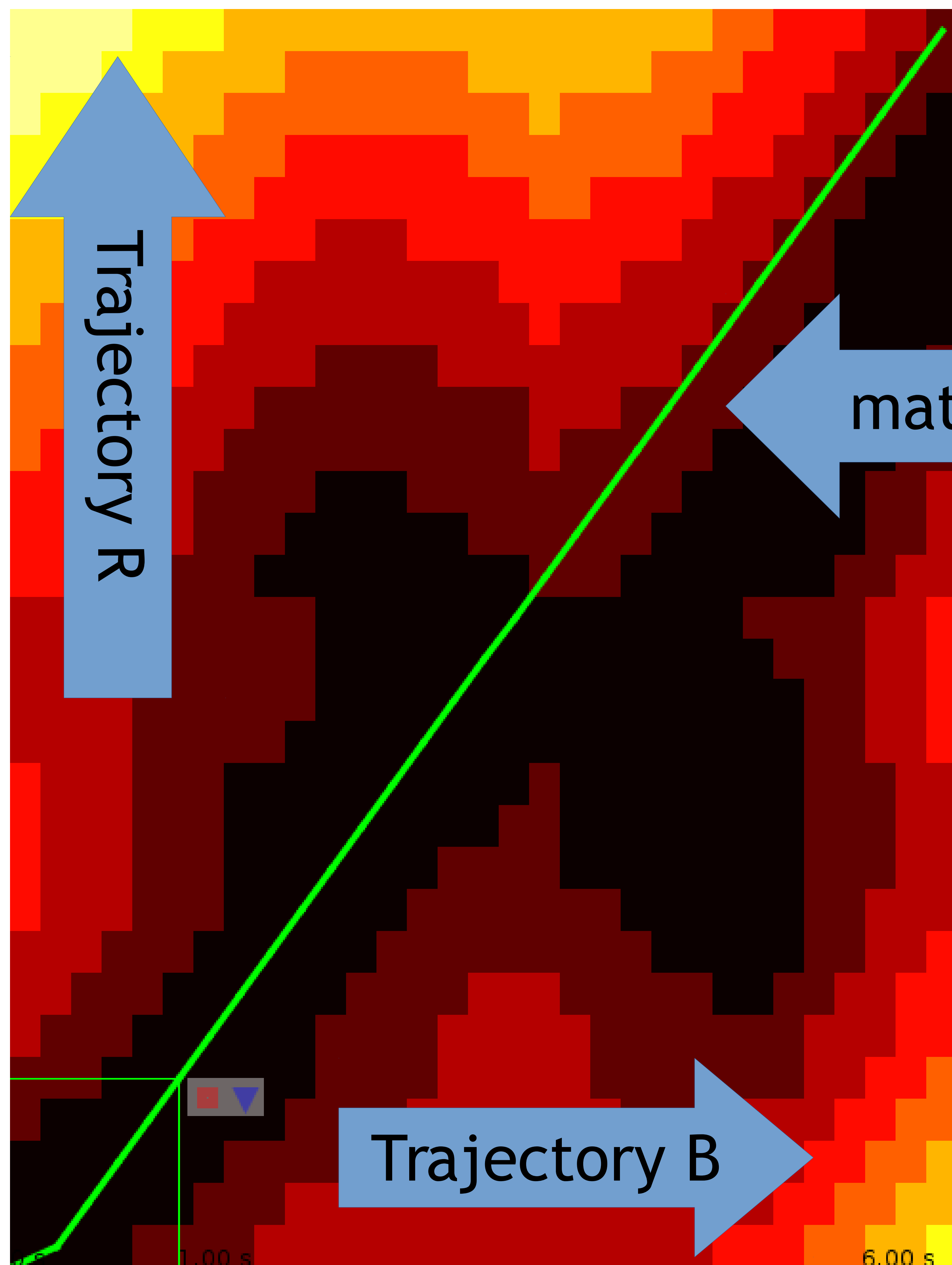
- Movement by **one trajectory**
- Response by **another trajectory**

## How to compute interaction?

Use a matching between the trajectories



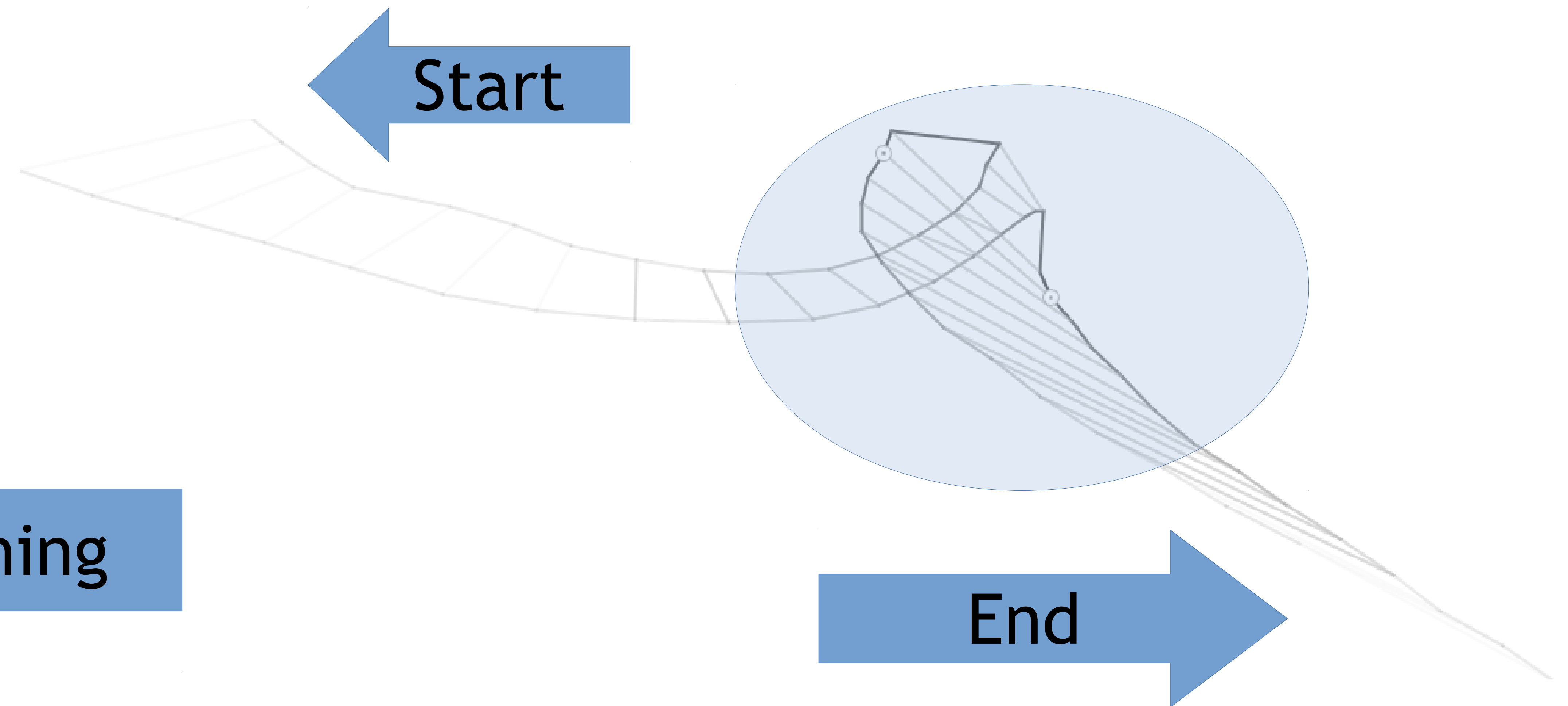
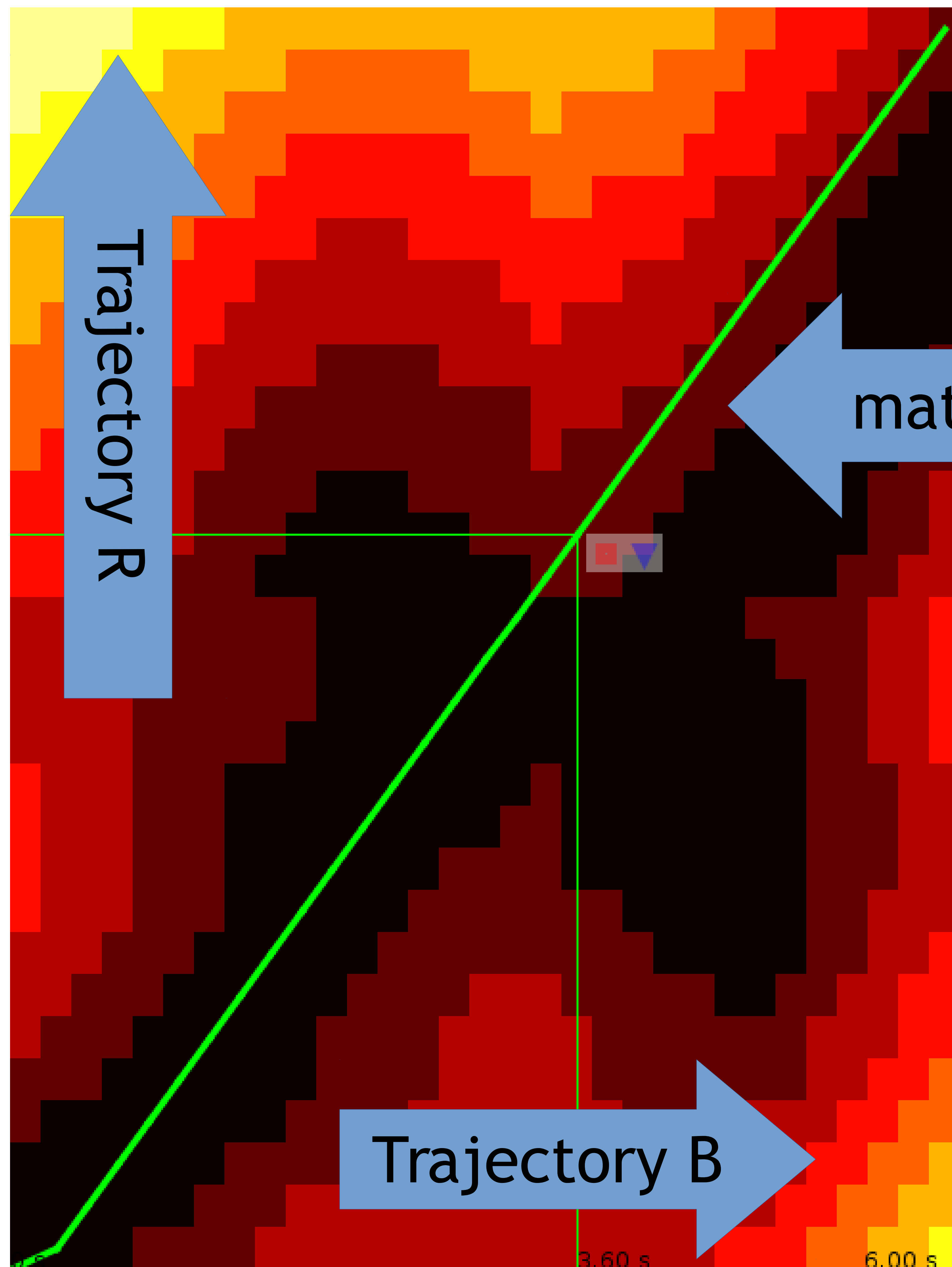




**Idea:** map points with same time-stamps

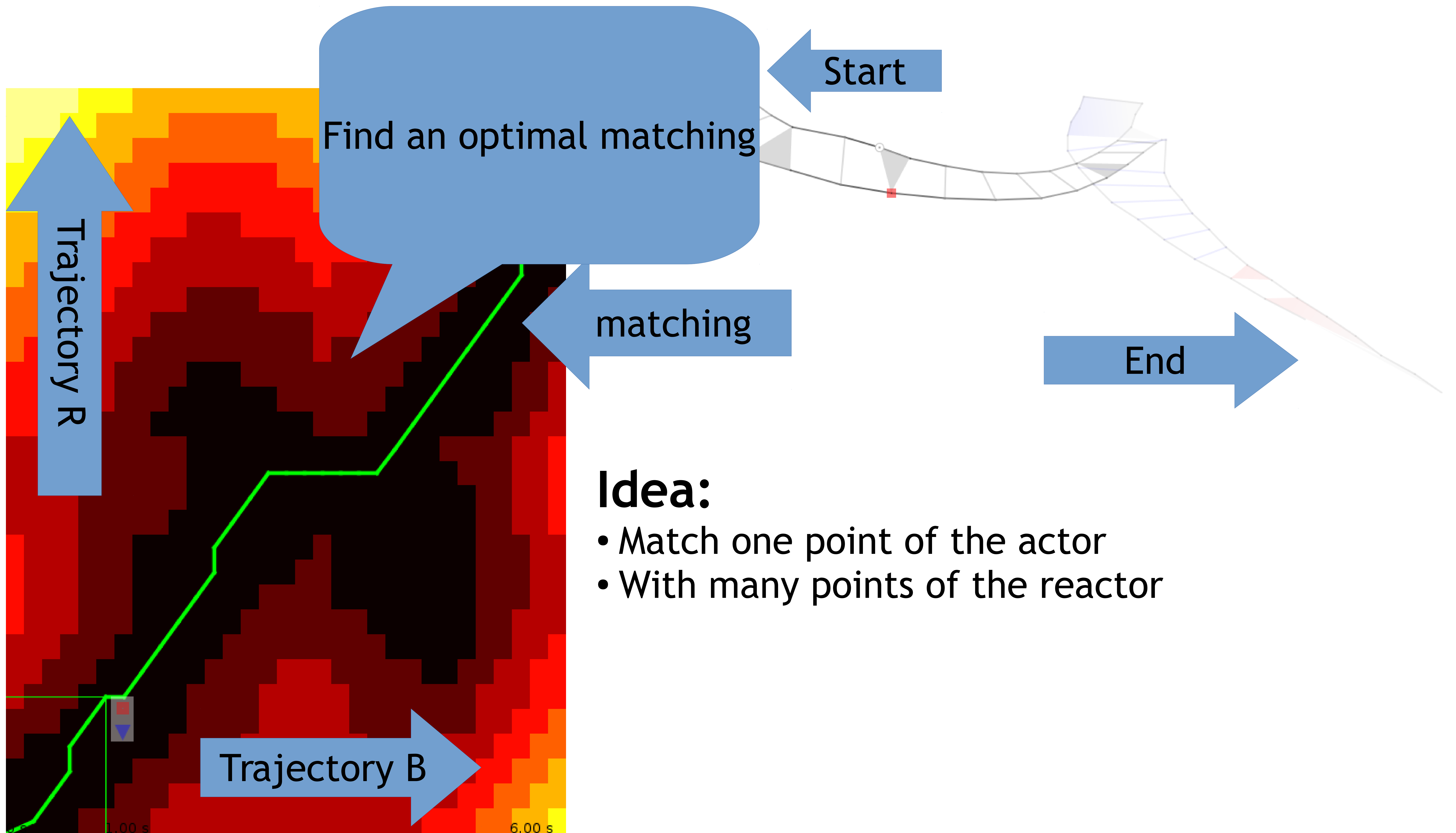
## Delay space

- All distances of pairs of points
- Encoded as a heated color body map



## Issues:

- Visual clutter in the matching
- Non optimal pairs for an index-based matching



## Idea:

- Match one point of the actor
- With many points of the reactor



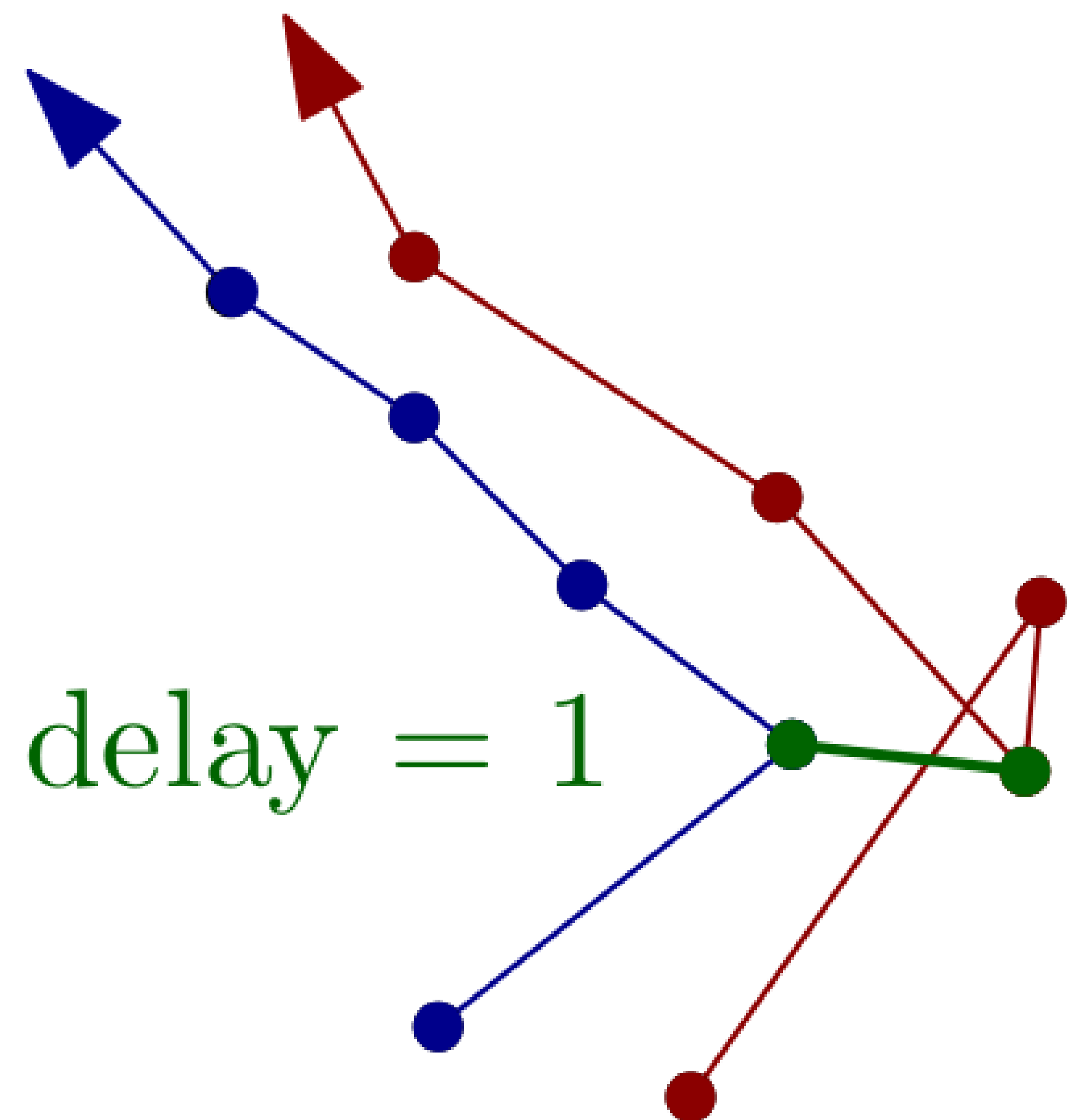


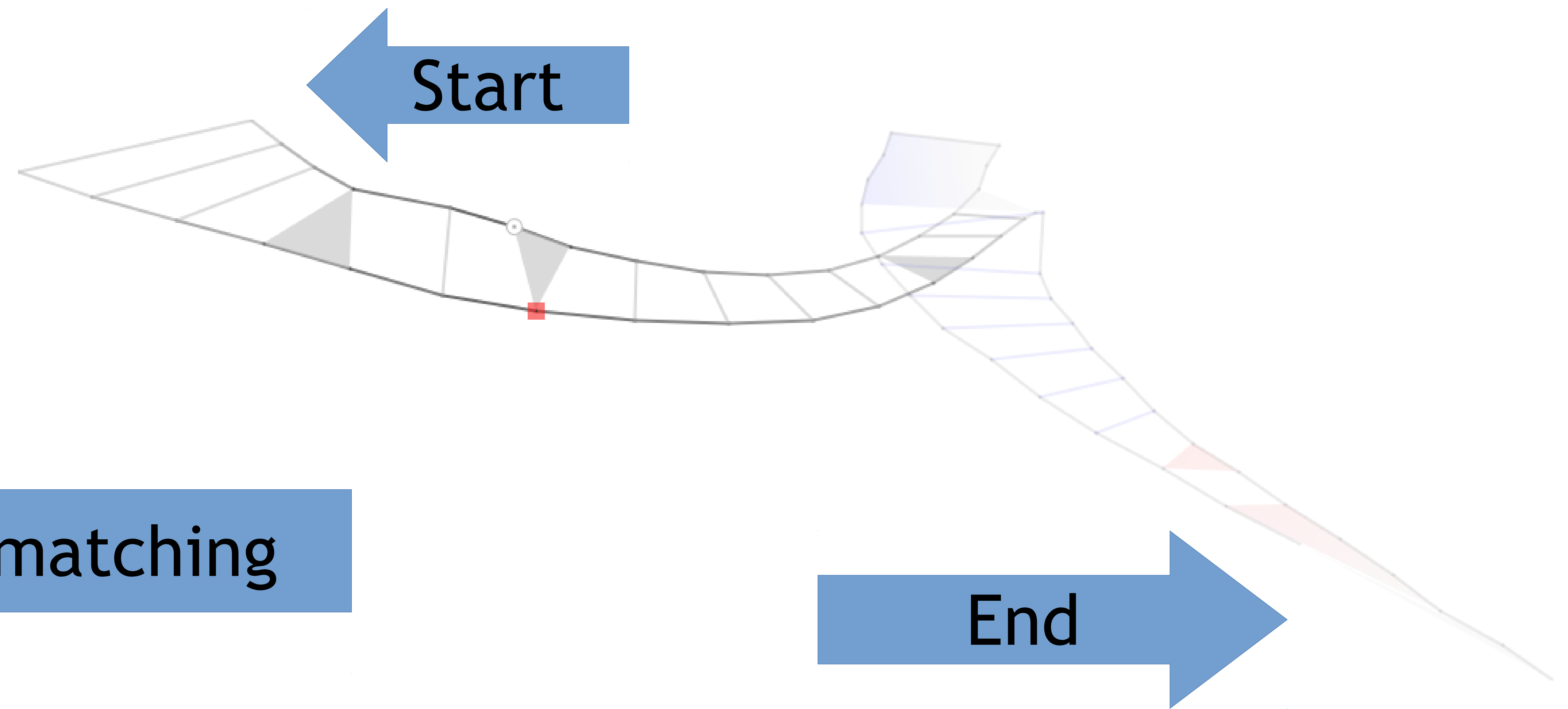
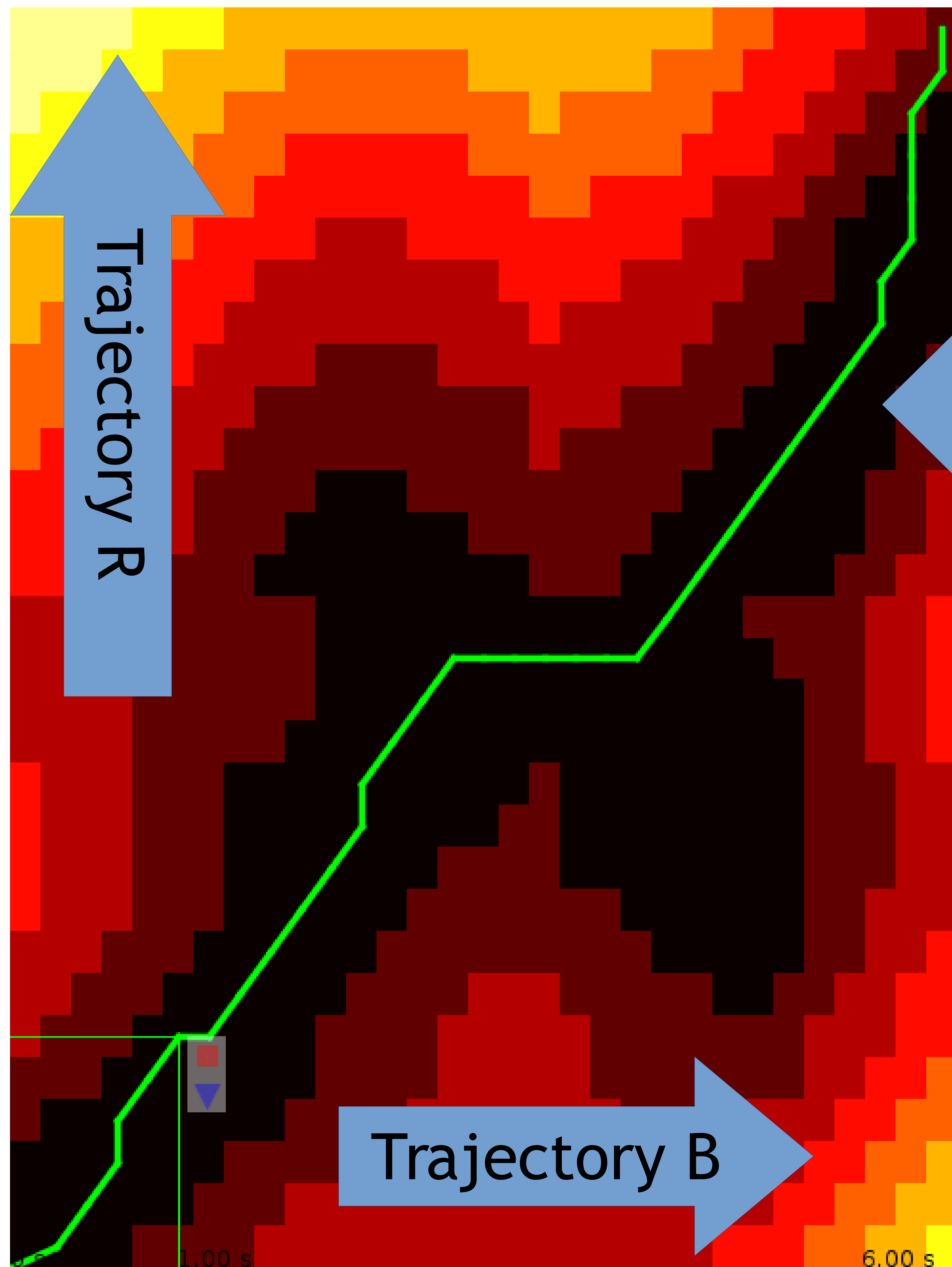
## What is interaction?

- Movement by **one trajectory**
- Response by **another trajectory**

## What is a delay?

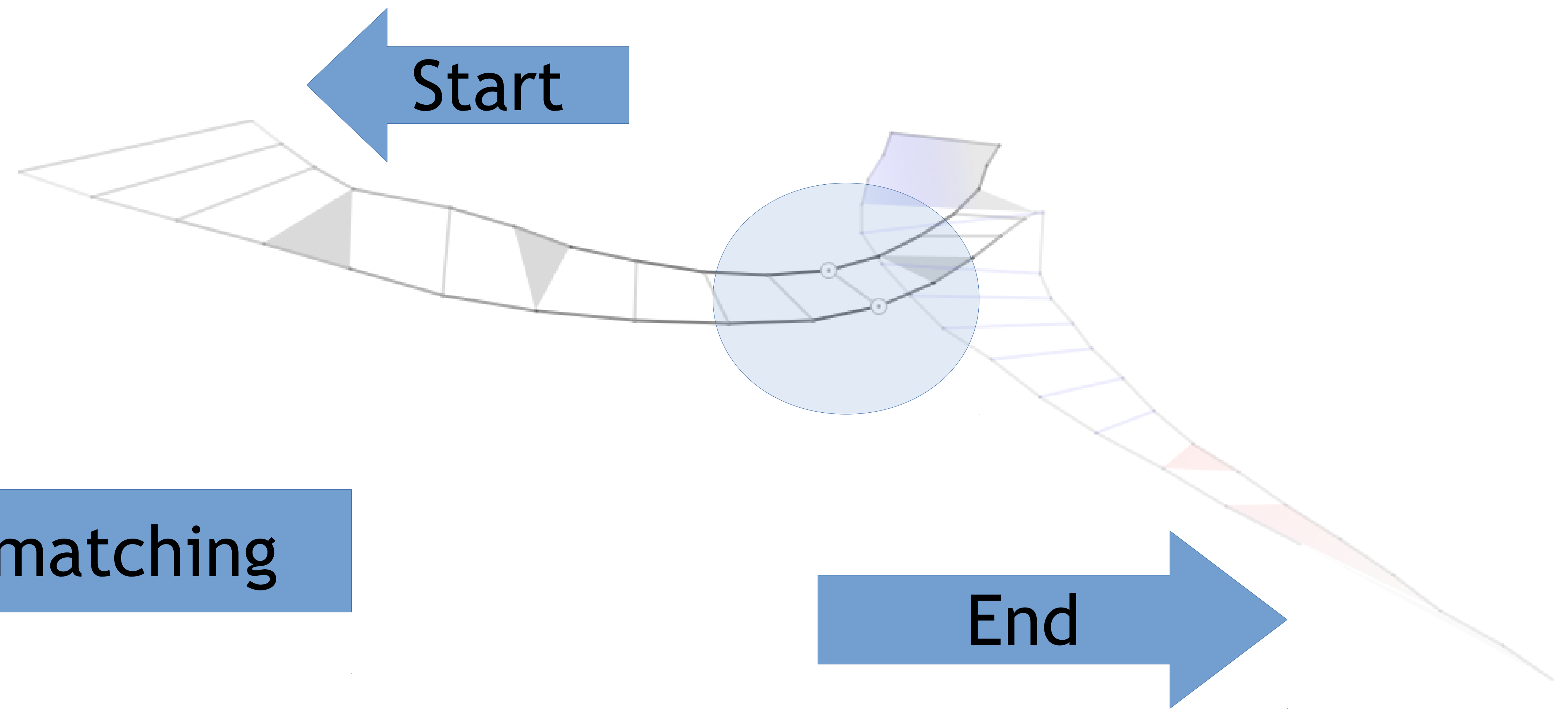
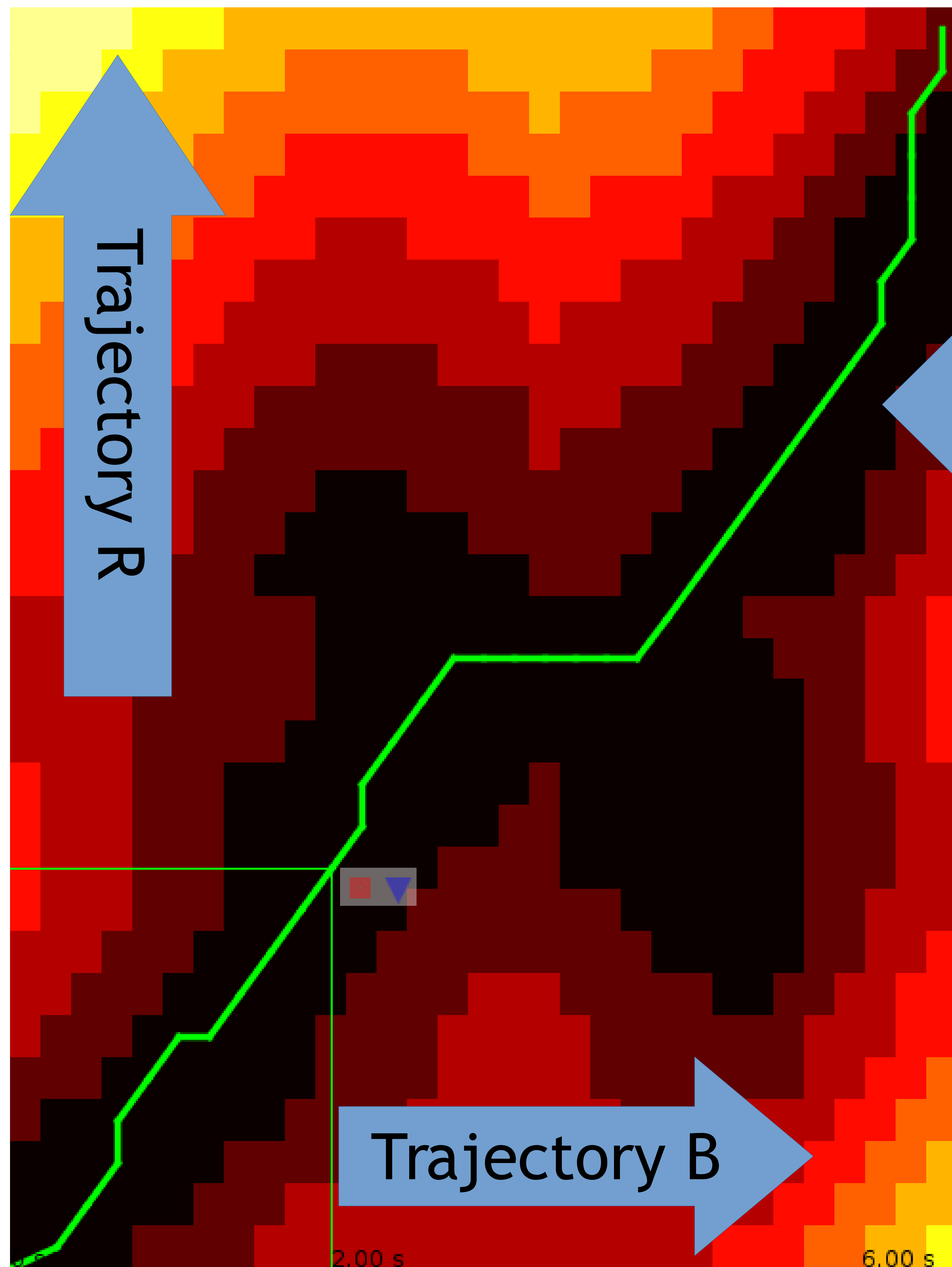
- **Delay**: difference of time stamps for a pair of points
- Occurs often in action-reaction interactions





## Technique:

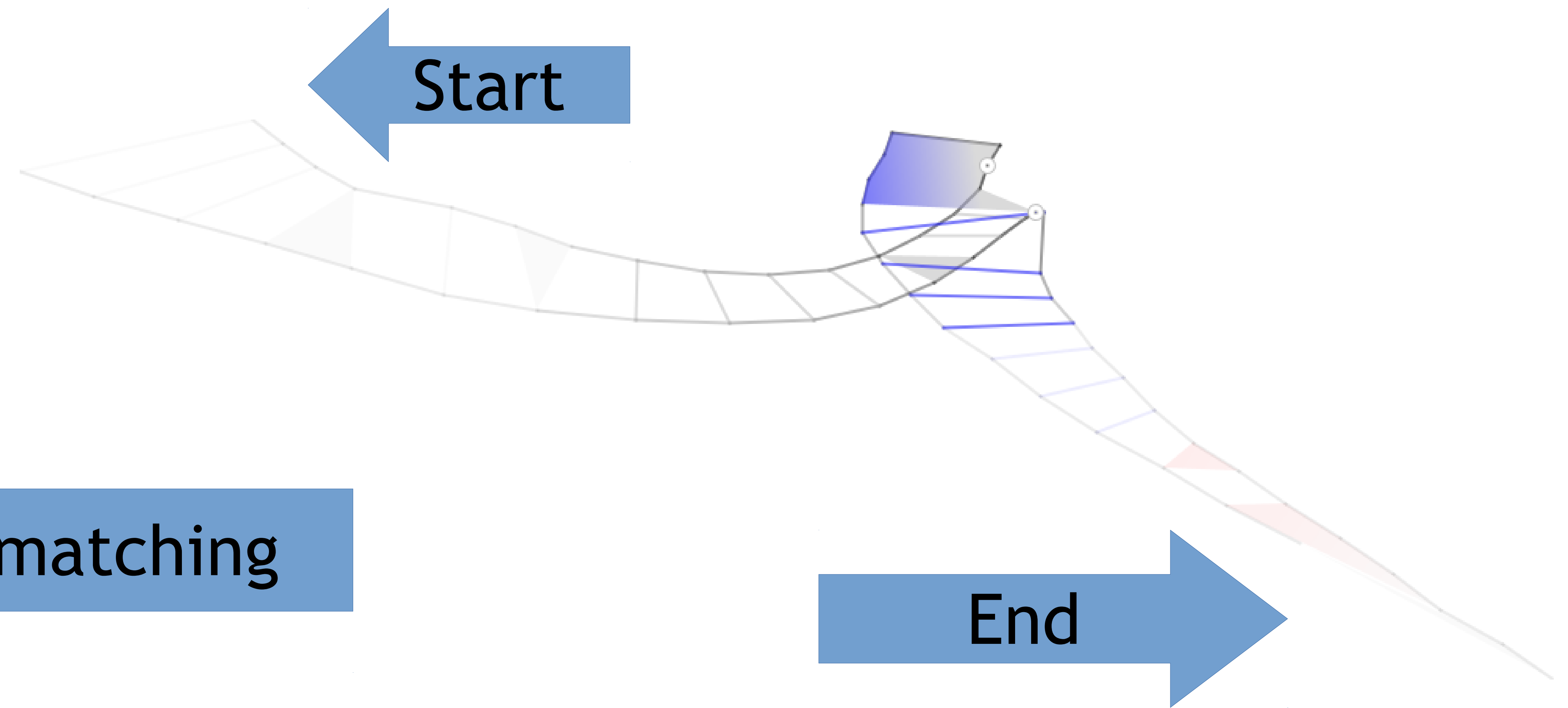
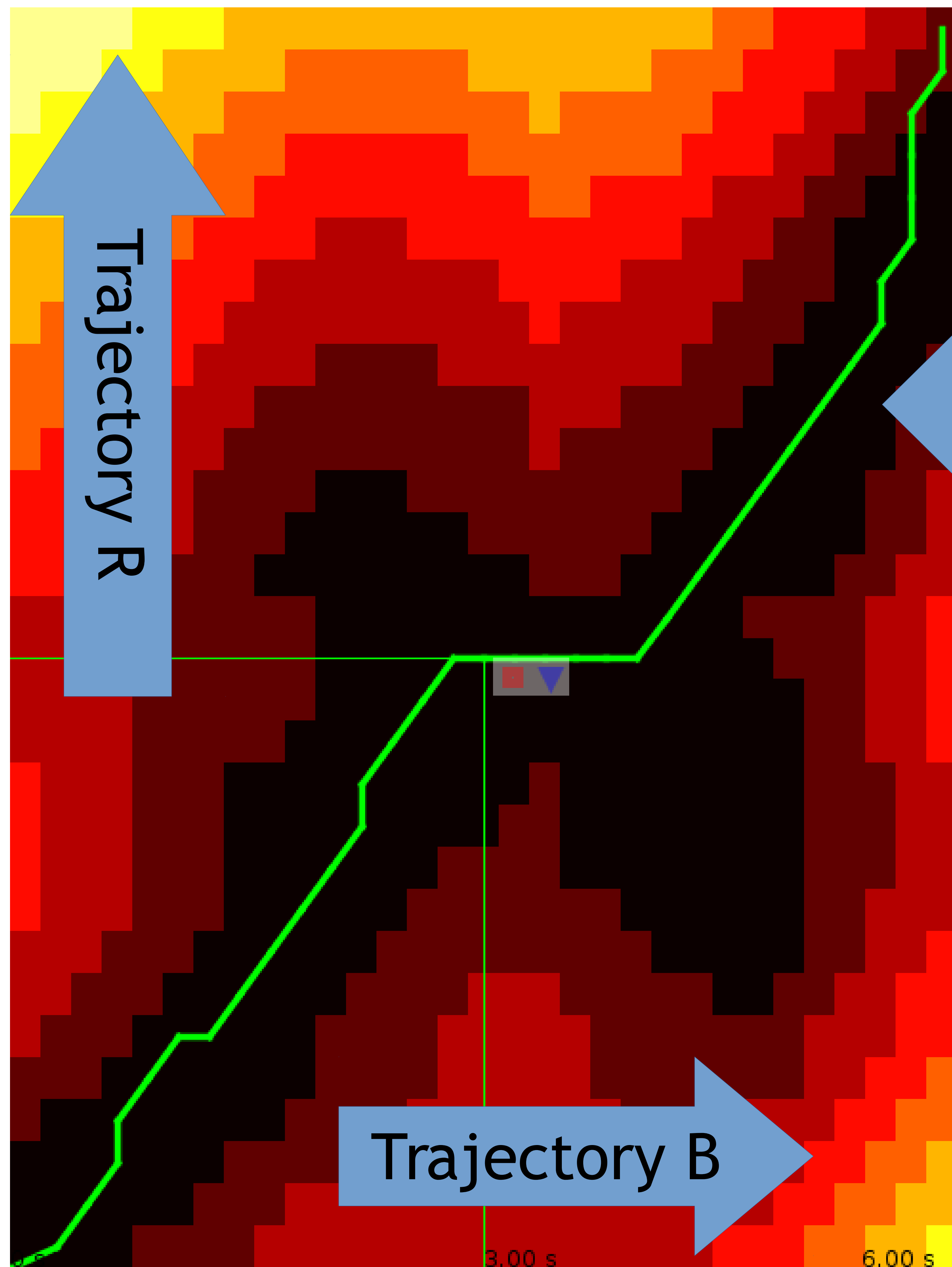
- Horizontal or vertical movements in the delay space
- Bundle those edges into a patch to avoid visual clutter
- A patch captures changes in the delay



## Delay:

- Diagonal movement in the delay space is a single edge
- No change in the delay

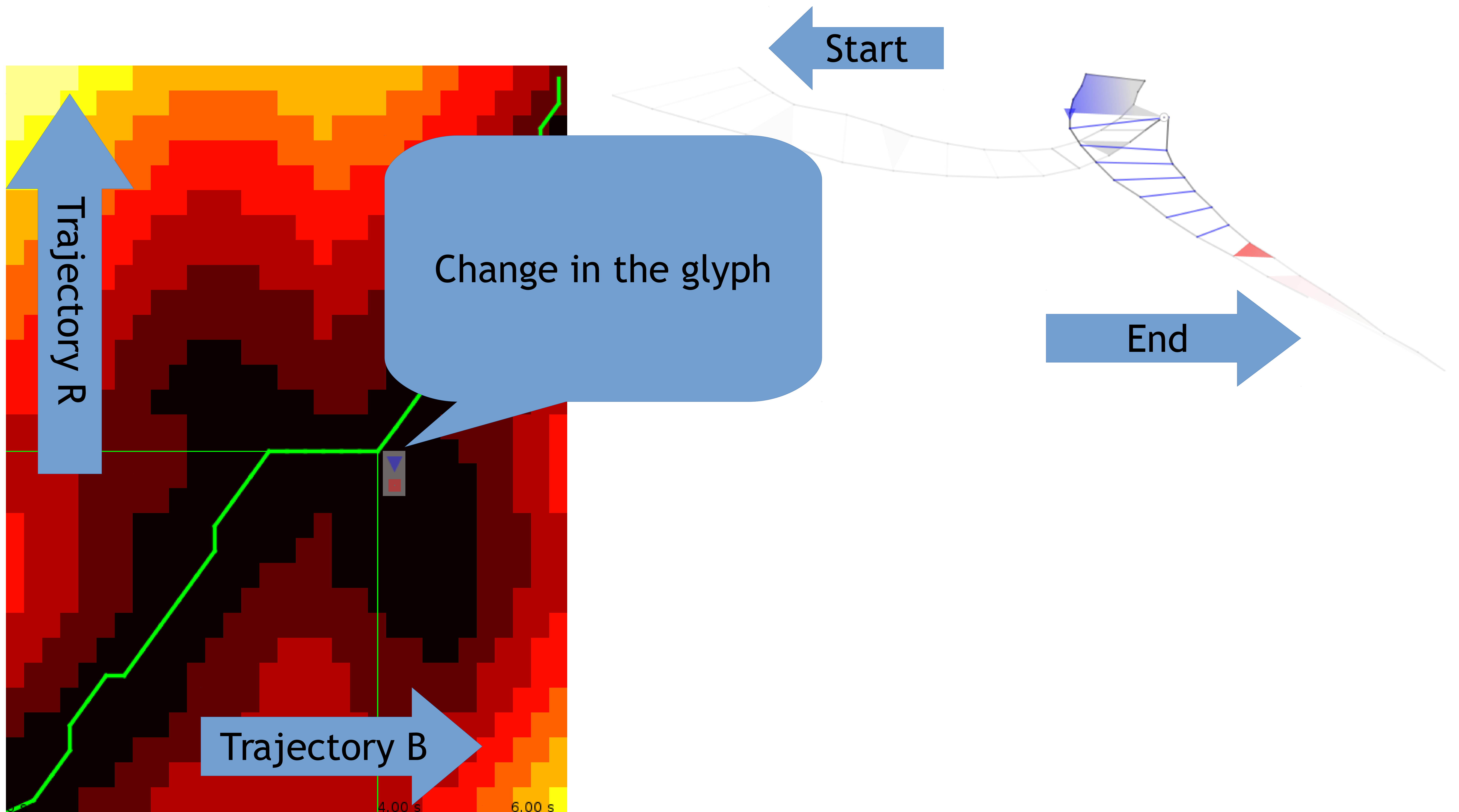


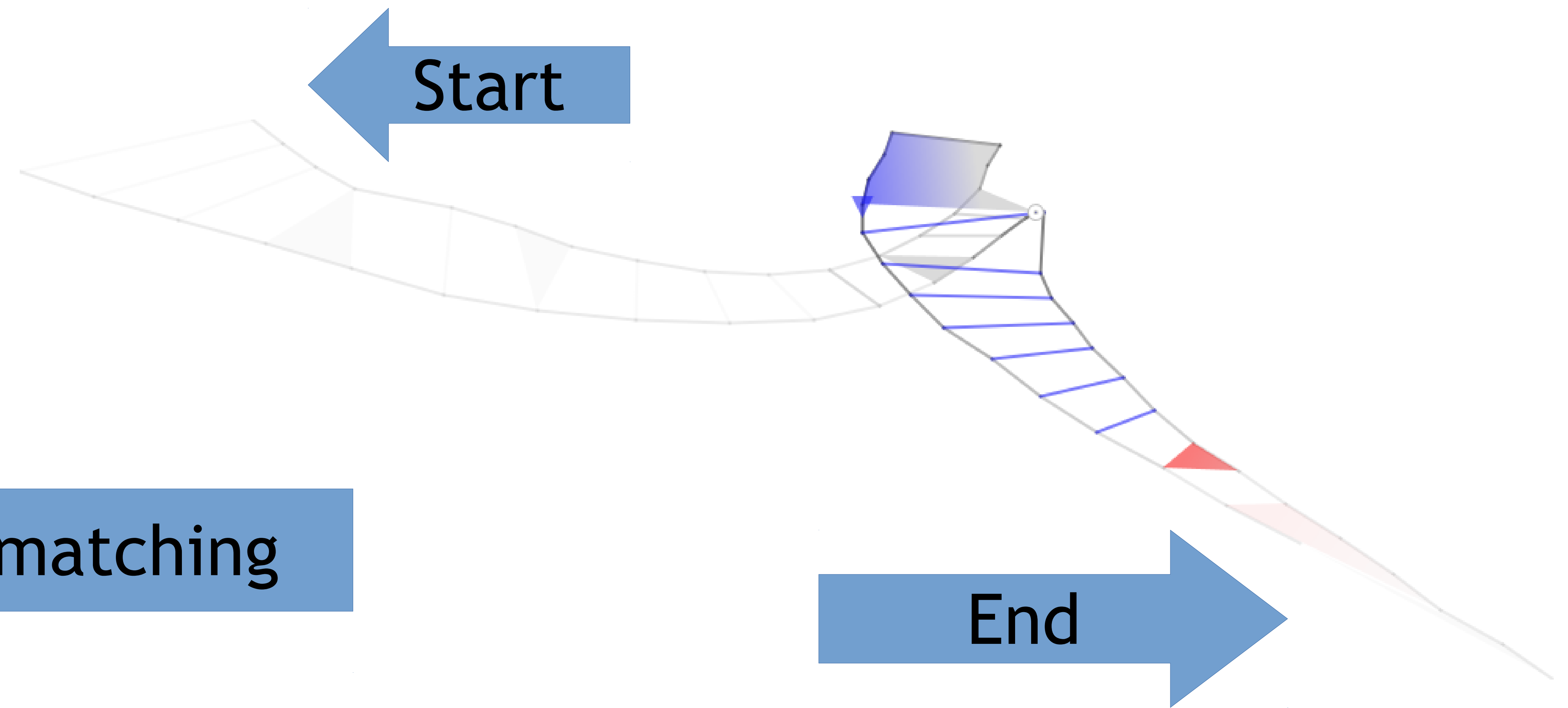
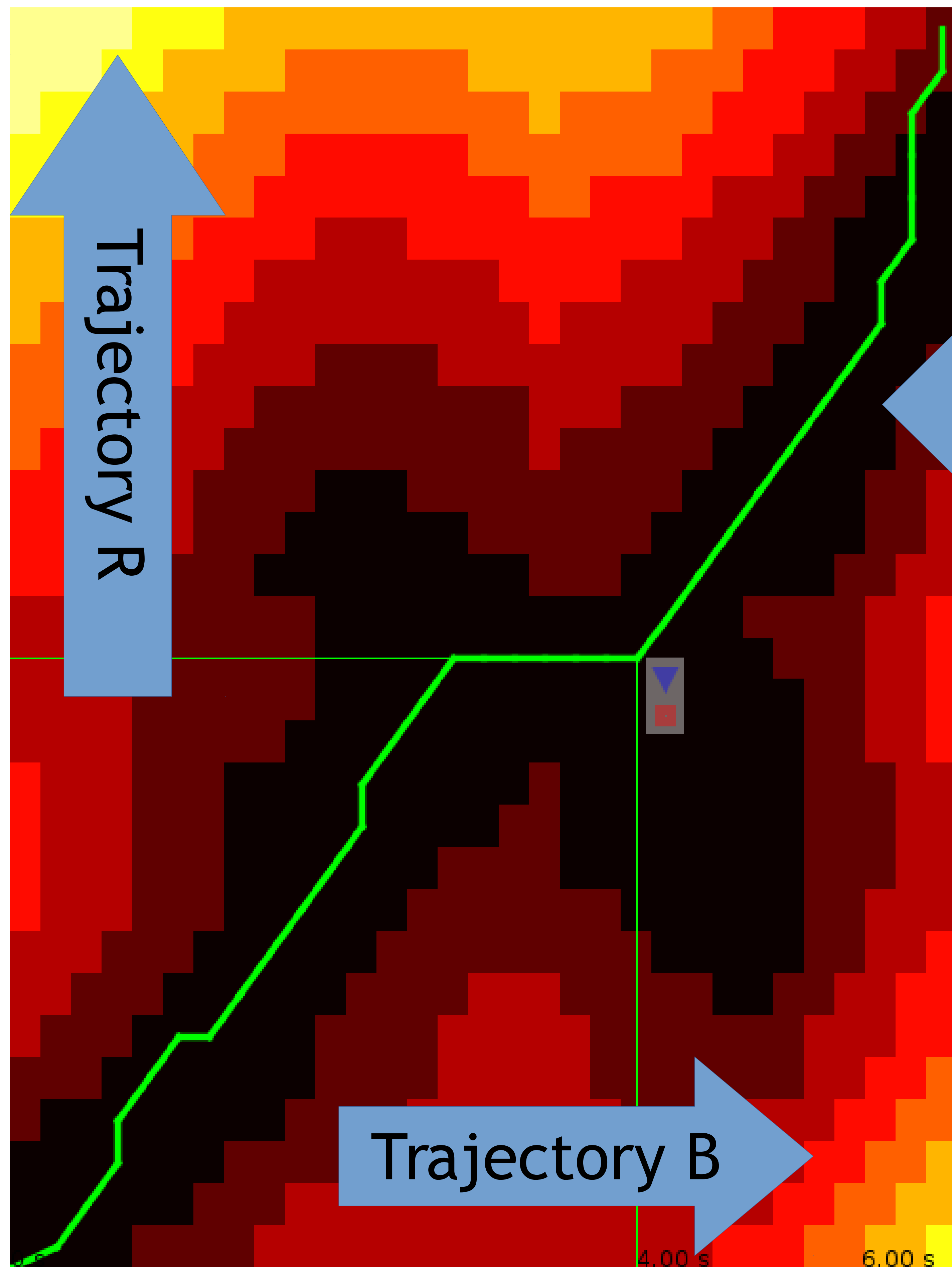


## Structure of a patch:

- Patch points to the source of the interaction
- Color of the patch indicates the relevance of the interaction event

# 1 to many matching of trajectories



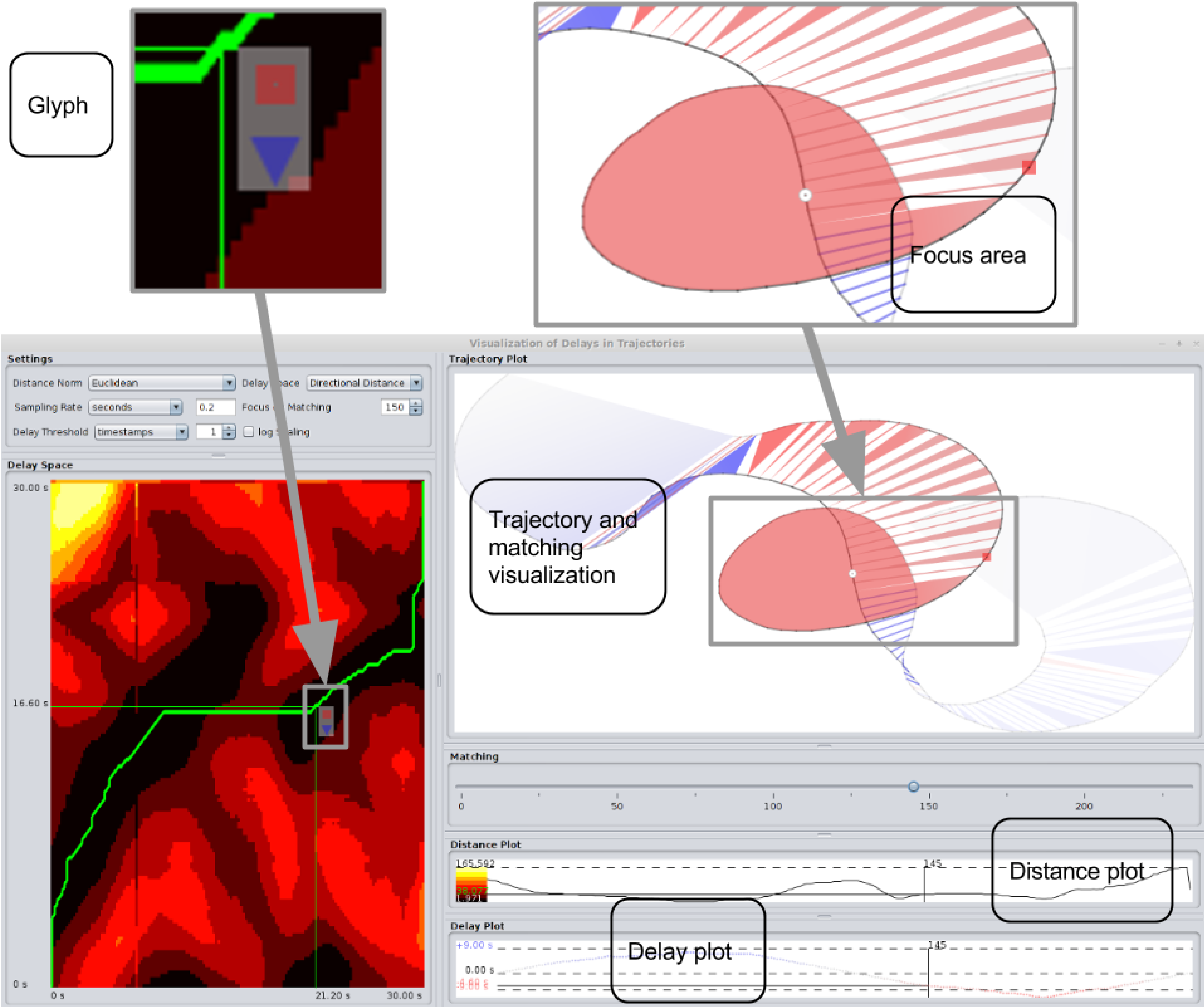


## Detecting a loop:

- Reaction by trajectory B
- Trajectory B increases delay to trajectory R



# Overview of the visual analytics tool



Delay space visualization

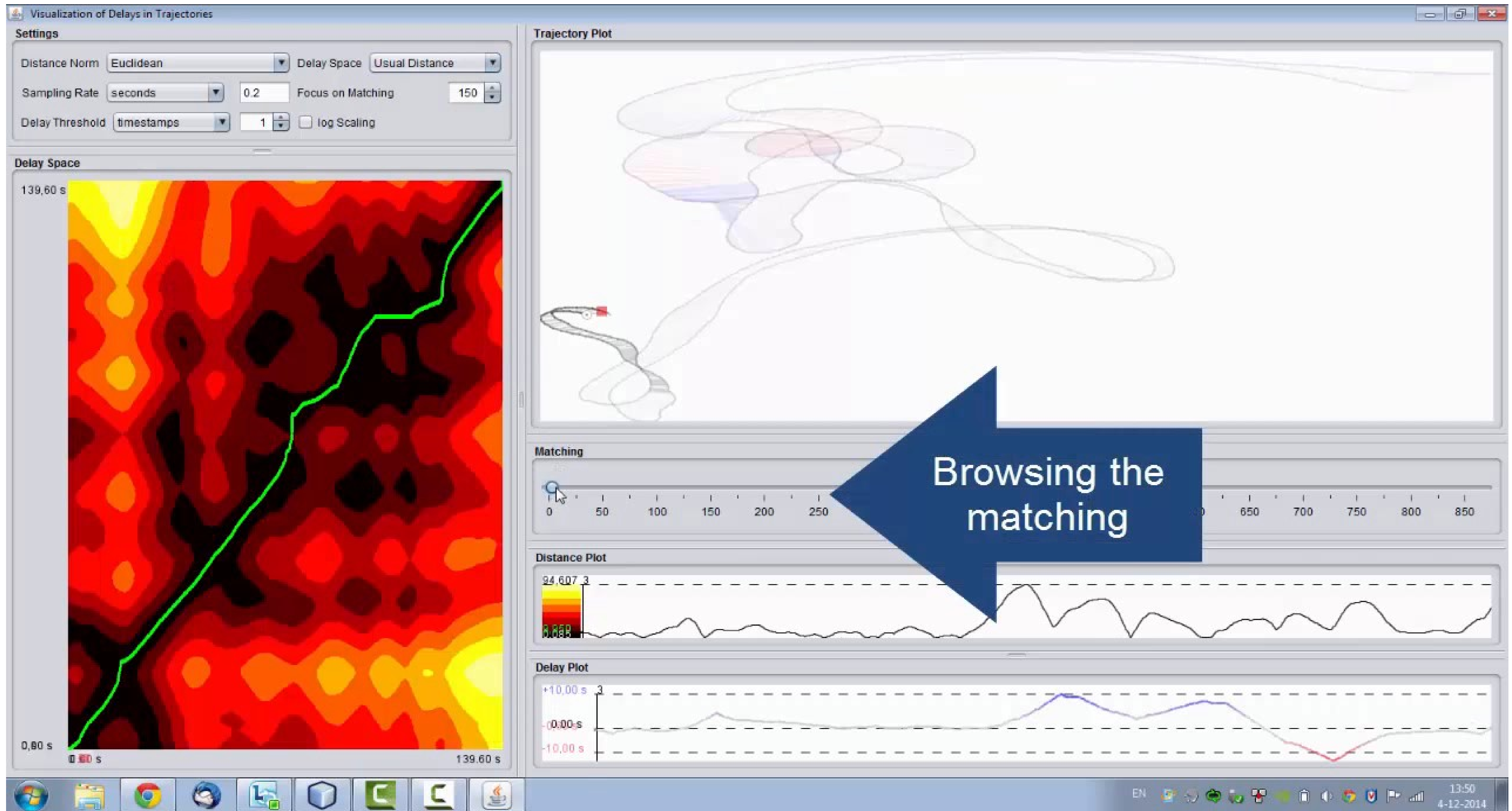
Glyph

Focus area

Trajectory and matching visualization

Distance plot

Delay plot



## Summary

- Prototype visual analytics tool for analyzing delays in trajectories
- Visual exploration as interconnected views
  - matching including the trajectories
  - delay space
  - delay plot
  - distance plot



## Future work

- Apply our approach in more scenarios
- Evaluate feedback from domain experts
- Generalize the concepts of interaction and delay to multiple trajectories



Thank you for your attention

TU/e

